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Murphy-Chutorian, E.; Doshi, A.; Trivedi, M.M.; [Intelligent Transportation Systems Conference, 2007. ITSC 2007. IEEE](#)
Sept. 30 2007-Oct. 3 2007 Page(s):709 - 714
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#4 ((eye* <sentence> orientation*) <and> driv*) <and> (head* <sentence> orientation*) <and> (vehicle* <or> car* <or> automobile*) <and> (driver* <sentence> orientation*) <and> (referen* <sentence> orient*) <in> pdfdata

#5 (((eye* <or> head*)<sentence> orientation*) <and> driv*) <and> (head* <sentence> orientation*) <and> (vehicle* <or> car* <or> automobile*) <and> (driver* <sentence> orientation*) <and> (referen* <sentence> orient*) <in> pdfdata

#6 (((eye* <or> head*)<sentence> orientation*) <and> driv*) <and> (head* <sentence> orientation*) <and> (vehicle* <or> car* <or> automobile*) <and> (driver* <sentence> orientation*) <and> (referen* <sentence> orient*) <in> pdfdata

#7 ((eye* <sentence> orientation*) <and> driv*) <and> (head* <sentence> orientation*) <and> (vehicle* <or> car* <or> automobile*) <and> (driver* <sentence> orientation*) <and> (referen* <sentence> orient*) <in> pdfdata

#8 (((eye* <or> head*)<sentence> orientation*) <and> driv*) <and> (head* <sentence> orientation*) <and> (vehicle* <or> car* <or> automobile*) <and> (driver* <sentence> orientation*) <and> (referen* <sentence> orient*) <in> pdfdata

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L22 and (driver\$ with orientation\$) and (referen\$ same orient\$)	4

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side by side		0	L23

*DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES;
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L25	L22 and (driver\$ with orientation\$) and (referen\$ same orient\$)	4 L25
L24	L22 and (driver\$ with orientation\$) and (referen\$ with orient\$)	2 L24
L23	L22 and (driver\$ near2 orientation\$) and (referen\$ with orient\$)	0 L23
L22	L18 or L19 or L21	119 L22

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5467104 4219847 4843568 4613942 5459793 4925189 4396945 4686374 6140980 6456262 5604818 4654872 5045843 6523955 5177511)![PN]	
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<u>L19</u> <u>L17</u>	4 <u>L19</u>
<i>DB=PGPB,USPT; THES=ASSIGNEE; PLUR=YES; OP=OR</i>	
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<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES;</i> <i>OP=OR</i>	
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<u>L13</u> (eye\$ near3 orientation\$) and driv\$ and (head\$ near3 orientation) and (vehicle\$ or car\$ or automobile\$) and (eye with mov\$ with data) and @pd<=20031015	0 <u>L13</u>
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